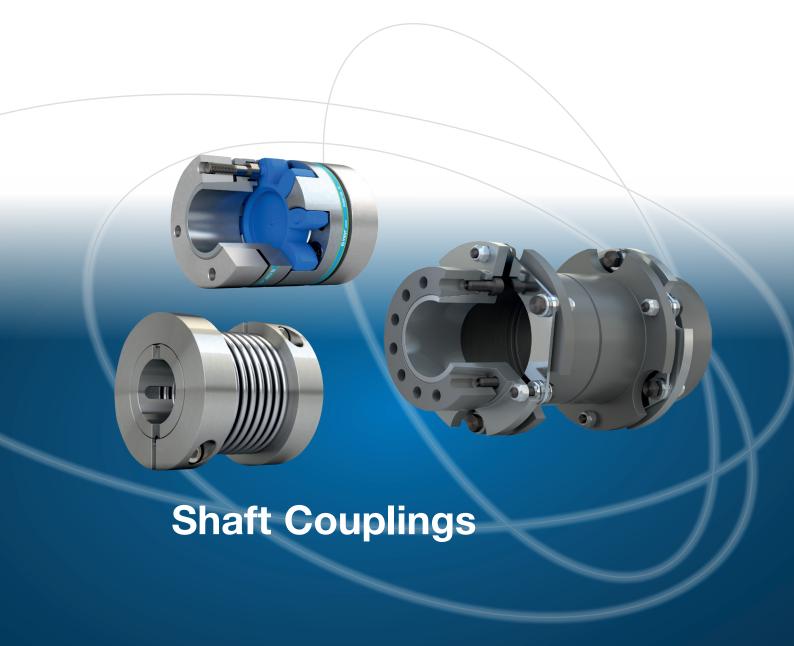


your reliable partner



# We safeguard the movements of this world





The Christian Mayr mill-construction business – founded in 1897.



Communications Centre mayr.com - opened in 2018.

# Specialists in power transmission for more than a century

mayr® power transmission is one of the most traditional and yet most innovative German companies in the field of power transmission. From modest beginnings in the year 1897, the family enterprise from the Allgäu region has developed into the world market leader. Today, approximately 700 employees work at the headquarters in Mauerstetten; about 1200 employees work for the company worldwide.

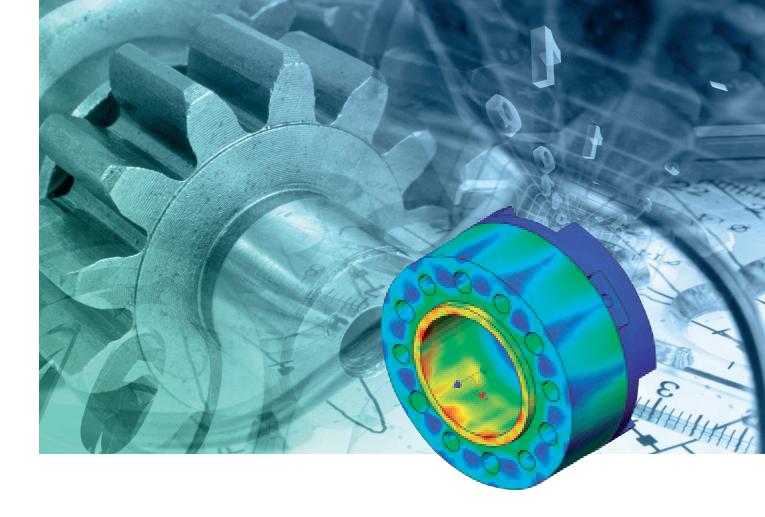
#### An unsurpassed standard product range

mayr® power transmission offers a wide variety of torque limiters, safety brakes, backlash-free shaft misalignment compensation couplings and high-quality DC drives. Regarding customer-specific requirements, too, the company possesses the expertise to develop customized and economical solutions. This is why numerous renowned machine manufacturers trust in holistic solutions by mayr® power transmission.

#### Represented worldwide

With eight subsidiaries in Germany, sales offices in the USA, France, Great Britain, Italy, Singapore and Switzerland as well as 36 additional country representatives, *mayr*<sup>®</sup> is available in all important industrial areas, guaranteeing optimum customer service around the globe.





# Tradition and innovation – the best of both worlds

Tradition and innovation do not contradict each other - on the contrary. They are the two supporting pillars which have guaranteed stability and reliability for generations. Long-term stability, independence as well as a good reputation and satisfied customers are important values for a family enterprise rich in tradition.

Therefore, we place emphasis on:

- Tested product quality,
- Optimum customer service,
- Comprehensive know-how,
- Global presence.
- Successful innovations and
- Effective cost management.

By pursuing our own objective of always offering our customers the technologically most advanced and most economical solution, we have been able to gain the trust of many leading industrial companies from all branches and from all over the world as a reliable partner.

Place your trust in our know-how and our more than 50 years of experience in torque limiters, safety brakes and shaft couplings.

# Never compromise on safety

We make no compromises where safety is concerned. Only top products of a perfect quality guarantee that no people are injured or machines damaged in case of malfunctions, collisions and other hazardous situations. The safety of your employees and machines is our motivation to always provide the best and most reliable clutches, couplings or brakes.

mayr® power transmission holds numerous ground-breaking patents, and is the global market or technological leader for

- application-optimised safety brakes, for example for passenger elevators, stage technology and gravity loaded axes
- torque limiters to protect against expensive overload damage and production losses and
- backlash-free servo couplings.







# Overview: Backlash-Free Shaft Couplings Types, Designs, Characteristics

| Application field                                 |       | Servo couplings             |                                       |  |  |  |
|---------------------------------------------------|-------|-----------------------------|---------------------------------------|--|--|--|
|                                                   |       | ROBA®-DS<br>Servo couplings | primeflex®<br>Steel bellows couplings |  |  |  |
|                                                   |       | Page 6                      | Page 8                                |  |  |  |
|                                                   |       |                             |                                       |  |  |  |
| Flexible element                                  |       | Disk pack                   | Steel bellows                         |  |  |  |
| Torque range                                      | [Nm]  | 35 – 150                    | 24 – 120                              |  |  |  |
| Max. permitted operating speed                    | [rpm] | 22500                       | 8000                                  |  |  |  |
| Shaft diameter                                    | [mm]  | 10 – 45                     | 10 – 45                               |  |  |  |
| Max. permanent operation temperature              | [°C]  | 100                         | 120                                   |  |  |  |
| ATEX design according to the directive 2014/34/EU |       | X                           |                                       |  |  |  |
| Product Catalogue                                 |       | K.950.V                     | P.933.V                               |  |  |  |





# Tested quality and reliability

mayr® products are subject to meticulous quality inspections. These include quality assurance measures during the design process as well as a comprehensive final inspection. Only the best, tested quality leaves our factory. All products are rigorously tested on test stands, and adjusted precisely to the requested values. An electronic database in which the measurement values are archived together with the associated serial numbers guarantees 100 % traceability. On request, we confirm the product characteristics with a test protocol.

The certification of our quality management according to DIN EN ISO 9001:2015 confirms the quality-consciousness of our colleagues at every level of the company.

# The Optimum Shaft Coupling for every Drive

Each drive has its own specific characteristics and therefore places different demands on the couplings which transmit the torque from one shaft to the second and which compensate for the resulting shaft misalignments. In most cases only backlash-free couplings are able to meet the requirements for high-speed, dynamic or reversing precision drives.

mayr® power transmission has three of the most established and most attractive backlash-free shaft couplings in its programme:

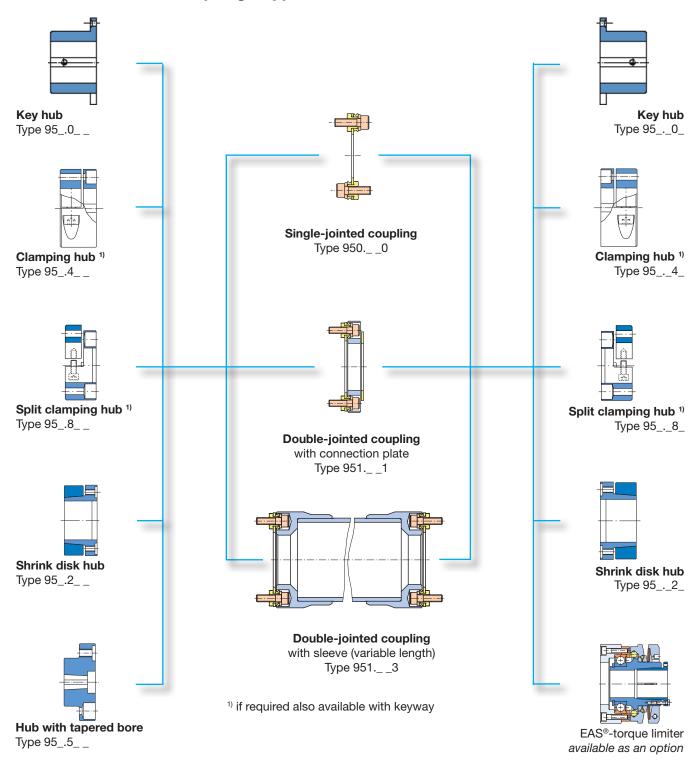
- Disk pack couplings,
- Steel bellows couplings and
- Elastomer couplings

Therefore, mayr<sup>®</sup> offers an optimum solution for many different drives.

| Servo co                | ouplings            | Industrial<br>couplings | Heavy load couplings | Torque<br>measurement<br>couplings |
|-------------------------|---------------------|-------------------------|----------------------|------------------------------------|
| smartflex <sup>®</sup>  | ROBA®-ES            | ROBA®-DS                | ROBA®-DS             | ROBA®-DSM                          |
| Steel bellows couplings | Elastomer couplings | All-steel couplings     | All-steel couplings  | Measurement couplings              |
| Page 10                 | Page 12             | Page 14                 | Page 16              | Page 18                            |
|                         |                     |                         |                      |                                    |
| Steel bellows           | Elastomer           | Disk pack               | Disk pack            | Disk pack                          |
| 16 – 700                | 4 – 1250            | 190 – 24000             | 22000 – 110000       | 190 – 1600                         |
| 10000                   | 28000               | 13500                   | 3600                 | 9500                               |
| 8 – 85                  | 6 – 80              | 14 – 170                | on request           | 14 – 110                           |
| 120                     | 100                 | 250                     | 250                  | 70                                 |
|                         | Х                   | Х                       |                      |                                    |
| K.932.V                 | K.940.V             | K.950.V                 | K.950.V              | K.950.V                            |



## ROBA®-DS servo couplings Type 95\_. \_ \_ \_



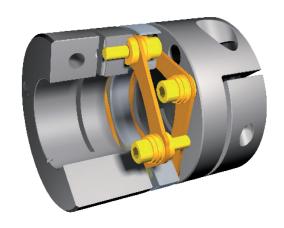
For detailed information, detailed technical data and dimensions, please see our product catalogue K.950.V\_ \_.\_ .



## ROBA®-DS - servo couplings

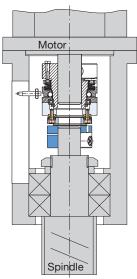
## **Characteristics and Advantages**

- ROBA®-DS servo couplings are made of steel and highstrength aluminium alloys – the basis of these extremely compact designs.
- Due to their high performance density, they transmit high torques at comparably low volumes.
- Their low mass moment of inertia also predestines ROBA®-DS servo couplings for highly dynamic drive systems with high speeds.
- The flexible disk pack compensates for shaft misalignments and transmits the torque backlash-free with a high torsional rigidity.
- ROBA®-DS servo couplings are absolutely wear-free and maintenance-free.





## **Installation Example**



ROBA®-DS shaft coupling combined with an EAS®-torque limiter.
Backlash-free and torsionally rigid torque transmission between the motor shaft and the spindle shaft.
Compensation of axial, radial and angular shaft misalignments.

| Too                           | hnical Data, Dimensions             |                   |                          |       | Si               | ze               |      |
|-------------------------------|-------------------------------------|-------------------|--------------------------|-------|------------------|------------------|------|
| iec                           | ninical Data, Dimensions            |                   |                          | 3     | 6                | 10               | 15   |
| Nom                           | inal torque 1)                      | $T_{KN}$          | [Nm]                     | 35    | 60               | 100              | 150  |
| Peak                          | torque <sup>2)</sup>                | T <sub>KS</sub>   | [Nm]                     | 52    | 90               | 150              | 225  |
| Alter                         | nating torque                       | T <sub>KW</sub>   | [Nm]                     | 21    | 36               | 60               | 90   |
| Oute                          | r diameter                          |                   | [mm]                     | 45    | 56               | 69               | 79   |
| q                             | Minimum bore                        |                   | [mm]                     | 10    | 14               | 19               | 25   |
| Clamping hub                  | Maximum bore                        |                   | [mm]                     | 20    | 28               | 35               | 42   |
| ping                          | Maximum speed 3)                    | n <sub>max</sub>  | [rpm]                    | 13500 | 10800            | 9000             | 7800 |
| am                            | Length single-jointed coupling      |                   | [mm]                     | 48.5  | 52.6             | 66.9             | 69.9 |
| ਠ                             | Min. length double-jointed coupling |                   | [mm]                     | 59    | 64.7             | 79.3             | 82.8 |
| 4)<br>ints                    | Axial displacement 5) 6)            | $\Delta K_{a}$    | [mm]                     | 0.5   | 0.7              | 0.9              | 1.1  |
| tted                          | Radial with connection plate        | $\Delta K_r$      | [mm]                     | 0.15  | 0.15             | 0.2              | 0.2  |
| Permitted 4)<br>nisalignments | misalignment 5 with special sleeve  | $\Delta K_{rH}$   | [mm]                     |       | Please contact t | he manufacturer. |      |
| P.e                           | Angular misalignment per disk pack  | $\Delta K_{w}$    | [°]                      | 1.0   | 1.0              | 1.0              | 1.0  |
| Tors                          | onal spring rigidity Disk pack      | C <sub>T LP</sub> | [10 <sup>3</sup> Nm/rad] | 17    | 35               | 60               | 145  |

- 1) Valid for max. permitted shaft misalignments.
- 2) Valid for unchanging load direction, max. load cycles  $\leq 10^5$ .
- 3) Not valid for coupling with special sleeve.

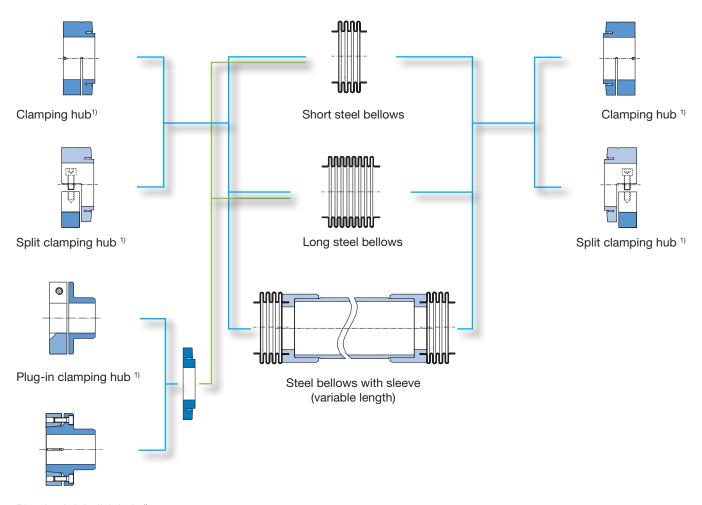
- 4) The permitted misalignments may not simultaneously reach their maximum values.
- 5) The values refer to couplings with 2 disk packs.
- 6) Only permitted as a static or virtually static value.



Also available in ATEX design according to the directive 2014/34/EU.



## primeflex® - steel bellows couplings



Plug-in shrink disk hub 1)

For detailed information, detailed technical data and dimensions, please see our product catalogue P.933.V\_\_..\_.

<sup>1)</sup> If required also available with keyway

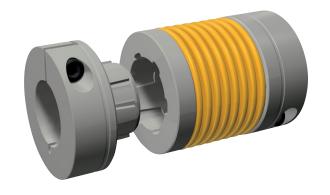
## primeflex® - steel bellows couplings

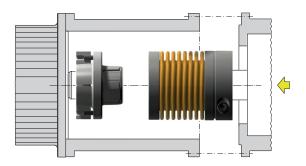
## **Characteristics and Advantages**

- Plug-in connection
- · Backlash-free
- Can be de-installed even after longer operating periods without damaging the steel bellows
- Extremely compact and very high performance density
- Easy to install via clamping or shrink disk connections
- Frictionally-locking und positive locking shaft-hub connections
- Excellent misalignment compensation capability
- Can be variably dimensioned via the modular system
- Cost-effective



## **Installation Example**





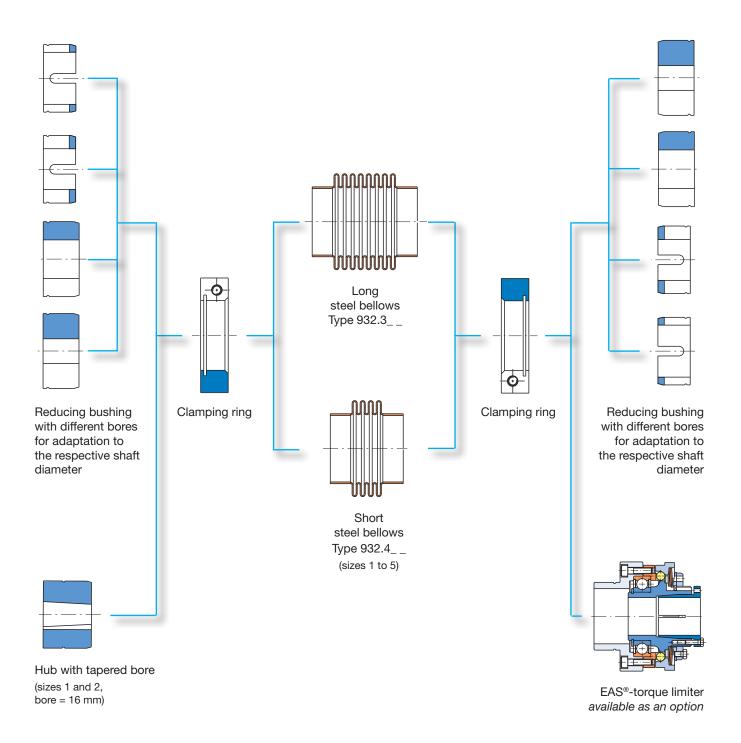
The primeflex®-steel bellows coupling transmits the torque backlash-free between the motor shaft and the gear shaft. By applying plug-in shrink disk hubs (see Installation Example) or plug-in clamping hubs, the primeflex®-steel bellows couplings can be mounted in areas which are difficult to access.

| Tool                                     | hnical Data Dim      | onoiono             |                  |                          |      | Size |      |
|------------------------------------------|----------------------|---------------------|------------------|--------------------------|------|------|------|
| iec                                      | hnical Data, Dim     | ensions             |                  |                          | 1    | 2    | 3    |
| Nom                                      | Nominal torque       |                     | T <sub>KN</sub>  | [Nm]                     | 24   | 60   | 120  |
| Oute                                     | Outer diameter       |                     |                  | [mm]                     | 47   | 60   | 79   |
| <u>e</u>                                 | Minimum bore         |                     |                  | [mm]                     | 12   | 19   | 25   |
| g ht                                     | Maximum bore         |                     |                  | [mm]                     | 25   | 35   | 45   |
| Clamping hub                             | Maximum speed        |                     | n <sub>max</sub> | [rpm]                    | 8000 | 6000 | 4000 |
| am                                       | Longith              | Long steel bellows  |                  | [mm]                     | 77   | 93   | 117  |
| ਠ                                        | Length               | Short steel bellows |                  | [mm]                     | 62   | 74   | 92   |
| - 40                                     | Avial displacement   | Long steel bellows  | $\Delta K_{a}$   | [mm]                     | 0.2  | 0.25 | 0.25 |
| ants                                     | Axial displacement   | Short steel bellows | $\Delta K_a$     | [mm]                     | 0.1  | 0.15 | 0.15 |
| Permitted <sup>1)</sup><br>nisalignments | Dadial misslianment  | Long steel bellows  | $\Delta K_r$     | [mm]                     | 0.2  | 0.3  | 0.3  |
| in in                                    | Radial misalignment  | Short steel bellows | $\Delta K_r$     | [mm]                     | 0.1  | 0.1  | 0.1  |
| nis:                                     | Angular              | Long steel bellows  | $\Delta K_{w}$   | [°]                      | 1    | 1    | 1    |
|                                          | misalignment         | Short steel bellows | $\Delta K_{w}$   | [°]                      | 1    | 1    | 1    |
| Tavai                                    | and anvine visidity  | Long steel bellows  | $C_{T}$          | [10 <sup>3</sup> Nm/rad] | 9    | 22   | 50   |
| iorsi                                    | onal spring rigidity | Short steel bellows | C <sub>T</sub>   | [10 <sup>3</sup> Nm/rad] | 18   | 44   | 100  |

<sup>1)</sup> The permitted misalignments may not simultaneously reach their maximum values.



## smartflex® - steel bellows couplings



For detailed information, detailed technical data and dimensions, please see our product catalogue K.932.V\_\_.\_.

## smartflex® - steel bellows couplings

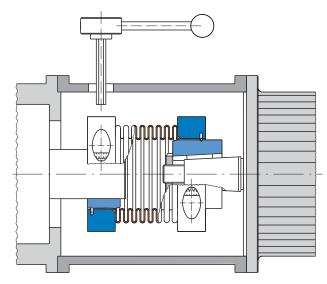
## **Characteristics and Advantages**

- smartflex®-steel bellows couplings compensate for axial, angular and radial shaft misalignments.
- Backlash-free shaft attachment, backlash-free torque transmission and high torsional rigidity provide high precision in the drive line.
- The easy and fast shaft attachment saves installation time.
- Due to the ingeniously simple set-up, the priceperformance ratio is extremely advantageous.
- On radial shaft misalignment, the misalignment compensation capability of smartflex®-couplings is up to three times higher than the misalignment compensation capability of common steel bellows couplings.
- The high misalignment compensation capability eliminates the most common accident cause on previous generations of steel bellows.
- A flexible modular system minimises storage and provides high availability.





## **Installation Example**



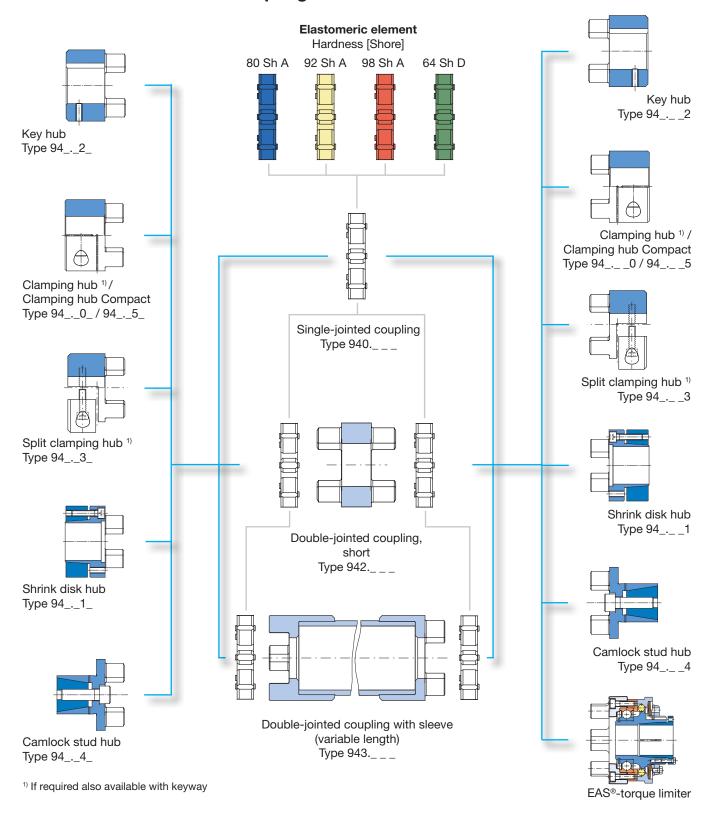
By applying clamping ring hubs, the smartflex®-steel bellows couplings can be mounted in areas which are difficult to access. Please provide an opening in the bell housing for the Allen wrench as depicted in the example.

| Tool                                  | hnical Data I  | Dimonolono          |                  |                          |       |      | Si   | ze   |      |      |
|---------------------------------------|----------------|---------------------|------------------|--------------------------|-------|------|------|------|------|------|
| iec                                   | hnical Data, I | Jimensions          |                  |                          | 0     | 1    | 2    | 3    | 4    | 5    |
| Nom                                   | inal torque    |                     | T <sub>KN</sub>  | [Nm]                     | 16    | 40   | 100  | 200  | 400  | 700  |
| Oute                                  | r diameter     |                     |                  | [mm]                     | 46    | 57   | 72   | 94   | 118  | 146  |
|                                       | Minimum bore   |                     |                  | [mm]                     | 8     | 11   | 16   | 18   | 30   | 40   |
| ing<br>or                             | Maximum bore   |                     |                  | [mm]                     | 19    | 25   | 36   | 50   | 62   | 85   |
| Reducing<br>bushing                   | Maximum spee   | d                   | n <sub>max</sub> | [rpm]                    | 10000 | 8000 | 6000 | 4000 | 3000 | 2500 |
| Re                                    | Longth         | Long steel bellows  |                  | [mm]                     | 49.5  | 59.3 | 72   | 90.3 | 115  | 124  |
|                                       | Length         | Short steel bellows |                  | [mm]                     | -     | 43.7 | 52.5 | 65.6 | 87   | 98   |
| (0                                    | Axial          | Long steel bellows  | $\Delta K_{a}$   | [mm]                     | 0.4   | 0.6  | 0.8  | 0.8  | 0.8  | 0.6  |
| ents                                  | displacement   | Short steel bellows | $\Delta K_{a}$   | [mm]                     | -     | 0.3  | 0.4  | 0.4  | 0.6  | 0.6  |
| Permitted <sup>1)</sup> isalignment   | Radial         | Long steel bellows  | $\Delta K_r$     | [mm]                     | 0.3   | 0.4  | 0.5  | 0.5  | 0.5  | 0.5  |
| rmi<br>alig                           | misalignment   | Short steel bellows | $\Delta K_r$     | [mm]                     | -     | 0.1  | 0.1  | 0.1  | 0.1  | 0.1  |
| Permitted <sup>1)</sup> nisalignments | Angular        | Long steel bellows  | $\Delta K_{w}$   | [°]                      | 3     | 3    | 3    | 3    | 1.5  | 1.0  |
| _                                     | misalignment   | Short steel bellows | $\Delta K_{w}$   | [°]                      | -     | 1.5  | 1.5  | 1.5  | 1.2  | 1.0  |
| Torsi                                 | ional spring   | Long steel bellows  | $C_{T}$          | [10 <sup>3</sup> Nm/rad] | 4     | 9    | 22   | 50   | 125  | 305  |
| rigid                                 | ity            | Short steel bellows | $C_{T}$          | [10 <sup>3</sup> Nm/rad] | -     | 18   | 44   | 100  | 168  | 380  |

<sup>1)</sup> The permitted misalignments may not simultaneously reach their maximum values.



## **ROBA®-ES – elastomer couplings**



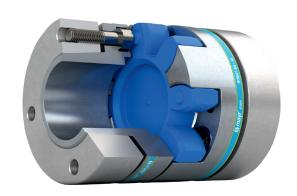
For detailed information, detailed technical data and dimensions, please see our product catalogue K.940.V\_\_.\_.

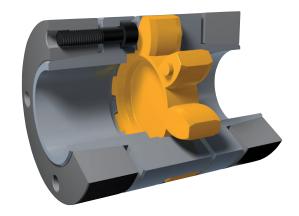


## ROBA®-ES - elastomer couplings

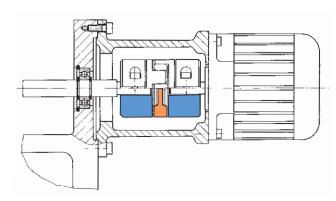
## **Characteristics and Advantages**

- ROBA®-ES couplings transmit the torque backlash-free via pre-tensioned elastomeric elements and compensate for shaft misalignments.
- Rigidity and damping behaviour are variable due to four elastomeric elements per size in different Shore hardnesses.
- ROBA®-ES elastomer couplings are insertable and are, therefore, also suitable for blind assembly.
- The couplings are maintenance-free, media-resistant and temperature-resistant. This guarantees the highest operational safety.
- ROBA®-ES couplings are torsionally flexible within narrow areas. However, in comparison to the toothed belt drive, their rigidity is still 2 to 4 times higher.





## **Installation Example**



The ROBA®-ES shaft coupling transmits the torque backlash-free between the motor shaft and the output shaft. It also compensates for axial, radial and angular shaft misalignments.

| Toobr                                    | ical Data Din           | oncione                            |                      |                         |       |          |        |         | Size     |          |        |         |       |
|------------------------------------------|-------------------------|------------------------------------|----------------------|-------------------------|-------|----------|--------|---------|----------|----------|--------|---------|-------|
| reciii                                   | ical Data, Din          | ierisioris                         |                      |                         | 14    | 19       | 24     | 28      | 38       | 42       | 48     | 55      | 65    |
| Nomina                                   | al torque Ela           | astomeric element hardness 98 Sh A | T <sub>KN</sub>      | [Nm]                    | 13    | 17       | 60     | 160     | 325      | 450      | 525    | 685     | 1040  |
| Peak to                                  | orque El                | astomeric element hardness 98 Sh A | T <sub>KS</sub>      | [Nm]                    | 26    | 34       | 120    | 320     | 650      | 900      | 1050   | 1370    | 2080  |
| Alterna                                  | ting torque Ele         | astomeric element hardness 98 Sh A | T <sub>KW</sub>      | [Nm]                    | See o | coupling | dimens | sioning | n the cu | urrent R | OBA®-E | S catal | ogue. |
| Outer o                                  | liameter                |                                    |                      | [mm]                    | 30    | 40       | 55     | 65      | 80       | 95       | 105    | 120     | 135   |
| ×                                        | Minimum bore            |                                    |                      | [mm]                    | 6     | 10       | 15     | 19      | 20       | 28       | 35     | 40      | 45    |
| ink di<br>hub                            | Maximum bore            |                                    |                      | [mm]                    | 14    | 20       | 28     | 38      | 45       | 50       | 60     | 70      | 75    |
| Shrink disk<br>hub                       | Maximum spee            | d                                  | n <sub>max</sub>     | [rpm]                   | 28000 | 21000    | 15500  | 13200   | 10500    | 9000     | 8000   | 6300    | 5600  |
| ळ                                        | Length single-j         | ointed coupling                    |                      | [mm]                    | 50    | 66       | 78     | 90      | 114      | 126      | 140    | 160     | 185   |
| , 4<br>4                                 |                         | Axial displacement                 | $\Delta K_{a}$       | [mm]                    | 1.0   | 1.2      | 1.4    | 1.5     | 1.8      | 2.0      | 2.1    | 2.2     | 2.6   |
| neric<br>ent<br>98 Sh                    | Permitted misalignments | Radial misalignment                | $\Delta K_r$         | [mm]                    | 0.09  | 0.06     | 0.1    | 0.11    | 0.12     | 0.14     | 0.16   | 0.17    | 0.18  |
| astomer<br>element<br>ness 98            | modilgrinionio          | Angular misalignment               | $\Delta K_{w}$       | [°]                     | 0.9   | 0.9      | 0.9    | 0.9     | 0.9      | 0.9      | 0.9    | 0.9     | 0.9   |
| Elastomeric<br>element<br>hardness 98 SP | Torsional spring        | static                             | C <sub>T stat.</sub> | $[10^3 \frac{Nm}{rad}]$ | 0.12  | 0.9      | 3.7    | 4.2     | 7.4      | 13.8     | 15.1   | 20.5    | 32.8  |
| har                                      | rigidity                |                                    | C <sub>T dyn.</sub>  |                         | 0.3   | 2.2      | 7.6    | 10.1    | 19.9     | 31.1     | 44.9   | 48.2    | 67.4  |

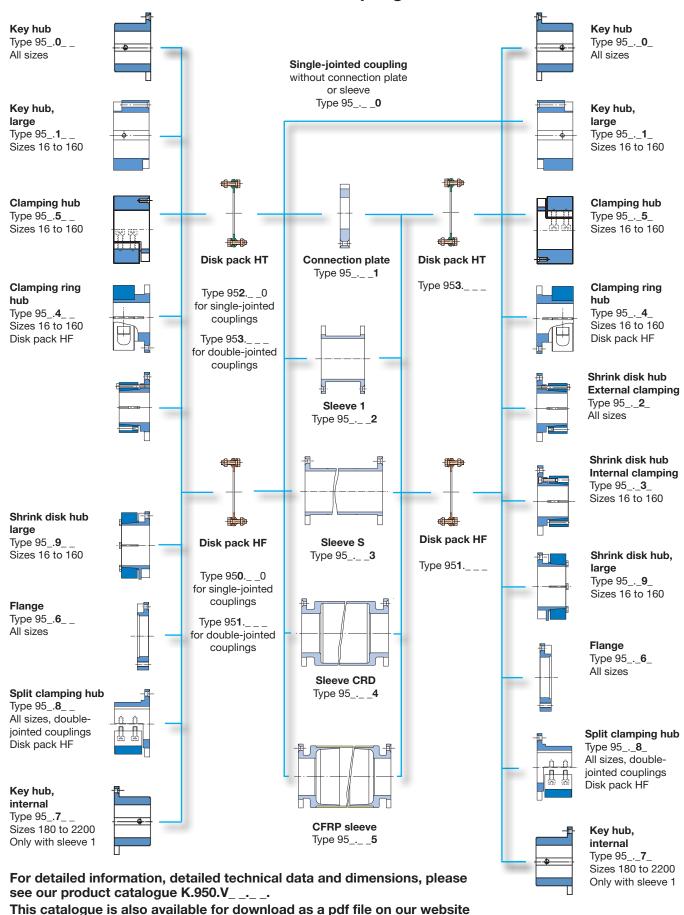
<sup>1)</sup> The permitted misalignments may not simultaneously reach their maximum values.



Also available in ATEX design according to the directive 2014/34/EU.



## ROBA® - DS backlash-free all-steel couplings



www.mayr.com.



## ROBA® - DS backlash-free all-steel couplings

## **Characteristics and Advantages**

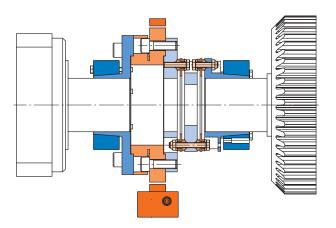
- ROBA®-DS couplings are not sensitive to alternating loads up to the full nominal torque.
- Due to their high performance density, they have a low mass moment of inertia.
- Backlash-free torque transmission with a constantly high torsional rigidity up to the nominal torque
- The full nominal torque can be used, even on alternating torques and shaft misalignments.
- High misalignment compensation capability at low restoring forces
- ROBA®-DS couplings are extremely robust and can therefore be used even under difficult conditions.
- A wide range of variants for optimum configuration



ROBA®-DS shaft coupling combined with an EAS®-torque limiter in a gear test stand manufactured by the company EGM (Entwicklungsgesellschaft für Montagetechnik GmbH).



## **Installation Example**



By using special adaptor flanges, different measuring flanges (for torque measurement) can be integrated into ROBA®-DS couplings.

| Too                                         | huisal Data I          | Dimonolono            |                   |                          |       |       |       |       |        | Si      | ze     |         |       |       |       |       |
|---------------------------------------------|------------------------|-----------------------|-------------------|--------------------------|-------|-------|-------|-------|--------|---------|--------|---------|-------|-------|-------|-------|
| iec                                         | hnical Data, I         | Jimensions            |                   |                          | 16    | 25    | 40    | 64    | 100    | 160     | 180    | 300     | 500   | 850   | 1400  | 2200  |
| Nom                                         | inal torque 1)         |                       | T <sub>KN</sub>   | [Nm]                     | 190   | 290   | 450   | 720   | 1000   | 1600    | 2100   | 3500    | 5800  | 9500  | 15000 | 24000 |
| Peak                                        | ( torque <sup>2)</sup> |                       | T <sub>KS</sub>   | [Nm]                     | 285   | 435   | 675   | 1080  | 1500   | 2400    | 3150   | 5250    | 8700  | 14250 | 22500 | 36000 |
| Oute                                        | er diameter            |                       |                   | [mm]                     | 77    | 89    | 104   | 123   | 143    | 167     | 143    | 167     | 198   | 234   | 274   | 314   |
| V                                           | Minimum bore           |                       |                   | [mm]                     | 14    | 20    | 25    | 30    | 35     | 40      | 42     | 50      | 60    | 70    | 80    | 100   |
| disk                                        | Maximum bore           |                       |                   | [mm]                     | 45    | 52    | 60    | 70    | 90     | 100     | 75     | 85      | 100   | 120   | 140   | 170   |
| nk c                                        | Maximum spee           | ed <sup>3)</sup>      | n <sub>max</sub>  | [rpm]                    | 13600 | 11800 | 10100 | 8500  | 7300   | 6200    | 7300   | 6200    | 5200  | 4400  | 3800  | 3300  |
| Shrink                                      | Min. length sing       | gle-jointed coupling  |                   | [mm]                     | 77.1  | 87.2  | 98.4  | 109.6 | 120    | 131.6   | 141.2  | 161.2   | 202   | 244   | 276   | 317.8 |
| ()                                          | Min. length dou        | uble-jointed coupling |                   | [mm]                     | 96.2  | 106.4 | 120.8 | 137.2 | 148    | 165.2   | 172.4  | 194.4   | 242   | 295   | 334   | 383.6 |
| 4)<br>nts                                   | Axial displaceme       | ent <sup>5) 6)</sup>  | $\Delta K_{a}$    | [mm]                     | 1.1   | 1.3   | 1.5   | 1.8   | 2.1    | 2.5     | 1.0    | 1.2     | 1.4   | 1.6   | 1.9   | 2.2   |
| ed                                          |                        | with connection plate | $\Delta K_r$      | [mm]                     | 0.3   | 0.3   | 0.4   | 0.45  | 0.45   | 0.55    | 0.25   | 0.25    | 0.35  | 0.4   | 0.5   | 0.55  |
| nitt                                        | Radial misalignment 5) | with sleeve 1         | $\Delta K_{rH}$   | [mm]                     | 1.0   | 1.2   | 1.5   | 1.8   | 2.1    | 2.2     | 1.2    | 1.25    | 1.35  | 1.7   | 2     | 2.6   |
| Permitted 4) isalignments                   | with special sleeve    |                       | $\Delta K_{rH}$   | [mm]                     |       |       |       | Plea  | ase co | ntact t | he mai | nufactı | urer. |       |       |       |
| E Angular misalignment per disk pack ΔK [°] |                        | 1.0                   | 1.0               | 1.0                      | 1.0   | 1.0   | 1.0   | 0.5   | 0.5    | 0.5     | 0.5    | 0.5     | 0.5   |       |       |       |
| Torsi                                       | ional spring rigio     | lity Disk pack        | C <sub>T LP</sub> | [10 <sup>3</sup> Nm/rad] | 145   | 280   | 301   | 748   | 1135   | 1920    | 3000   | 3480    | 11900 | 20600 | 30150 | 46800 |

- Valid for changing load direction as well as for max. permitted shaft misalignment.
- Valid for unchanging load direction, max. load cycles ≤ 10<sup>5</sup>.
- 3) Not valid for coupling with special sleeve.

- 4) The permitted misalignments may not simultaneously reach their maximum values.
- 5) The values refer to couplings with 2 disk packs.
- 6) Only permitted as a static or virtually static value.



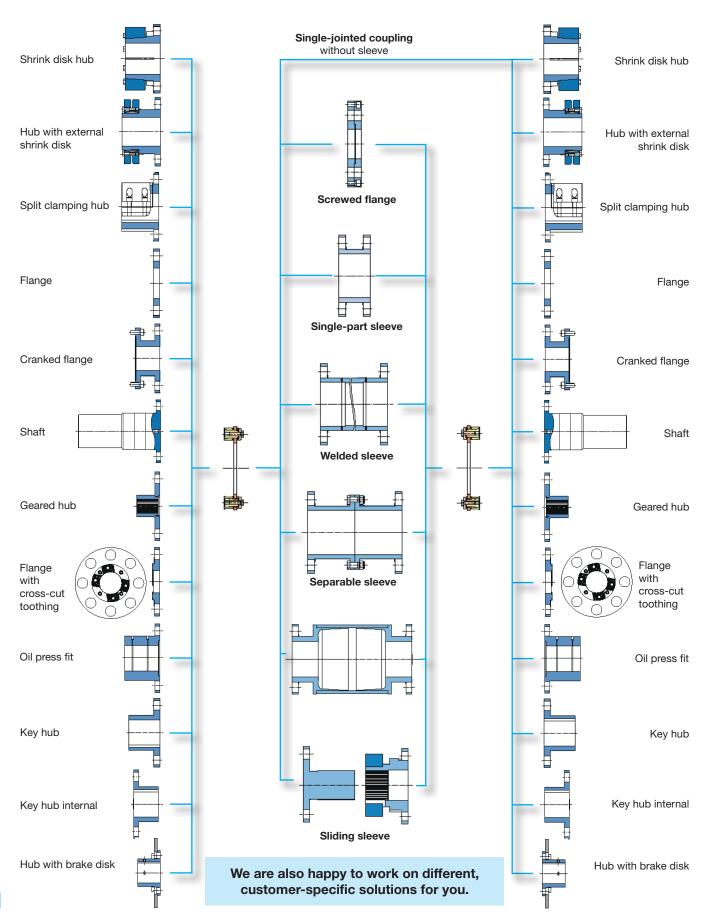
Also available in ATEX design according to the directive 2014/34/EU.



Also available in rustproof design.



# **ROBA®-DS – heavy load couplings Modular Structure**





## ROBA®-DS - heavy load couplings

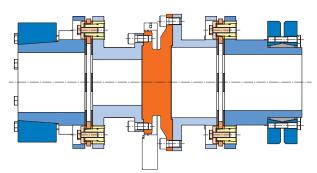
## **Characteristics and Advantages**

- Low screw tightening torques
- Can be installed / de-installed radially
- Easy and quick installation / de-installation
- No hydraulic installation tools required; can be installed with a torque wrench
- Backlash-free torque transmission
- FEM-optimized disk shape
- High torsional rigidity
- High performance density
- · Compensation of axial, angular and radial misalignments
- Wear and maintenance-free
- High flexibility through customer-specific hubs and sleeves





## **Installation Example**



The measurement flange is positioned between the two disk packs. This way, the measurement flange can be de-installed radially with the sleeve, for example for calibration, without de-installing the hubs. Backlash-free shaft-hub connection via shrink disk hub or hub with external shrink disks ensures maximum precision.

| Toohniaal Da                  | ta Dimensione                           |                    |       | Size                             |        |        |        |        |  |  |  |  |
|-------------------------------|-----------------------------------------|--------------------|-------|----------------------------------|--------|--------|--------|--------|--|--|--|--|
| Technical Data, Dimensions    |                                         |                    |       | 2200                             | 3300   | 5000   | 7300   | 11000  |  |  |  |  |
| Alternating torqu             | ue 1)                                   | T <sub>KW</sub>    | [Nm]  | 14700                            | 22000  | 33300  | 48700  | 73300  |  |  |  |  |
| Nominal torque                | 2)                                      | T <sub>KN</sub>    | [Nm]  | 22000                            | 33000  | 50 000 | 73 000 | 110000 |  |  |  |  |
| Peak torque 3)                |                                         | T <sub>KS</sub>    | [Nm]  | 44000                            | 66 000 | 100000 | 146000 | 220000 |  |  |  |  |
| Outer diameter                | Outer diameter [mm]                     |                    | 290   | 332                              | 378    | 431    | 492    |        |  |  |  |  |
| Maximum speed                 |                                         | n <sub>max</sub>   | [rpm] | 3600                             | 3100   | 2700   | 2400   | 2100   |  |  |  |  |
|                               | Axial displacement 5)                   | $\Delta K_{a}$     | [mm]  | 1.6                              | 1.7    | 2.1    | 2.3    | 2.3    |  |  |  |  |
| Permitted 4)<br>misalignments | Radial misalignment with special sleeve | $\Delta K_{rH}$    | [mm]  | Please contact the manufacturer. |        |        |        |        |  |  |  |  |
| madiigimenta                  | Angular misalignment per disk pack      | $\Delta K_{\rm w}$ | [°]   | 0.4                              | 0.4    | 0.4    | 0.4    | 0.3    |  |  |  |  |

<sup>1)</sup> Valid for changing load direction as well as for max. permitted shaft misalignment.

For detailed information, detailed technical data and dimensions, please see our product catalogue K.950.V\_\_.\_.\_.

<sup>2)</sup> Valid for unchanging load direction as well as for max. permitted shaft misalignment.

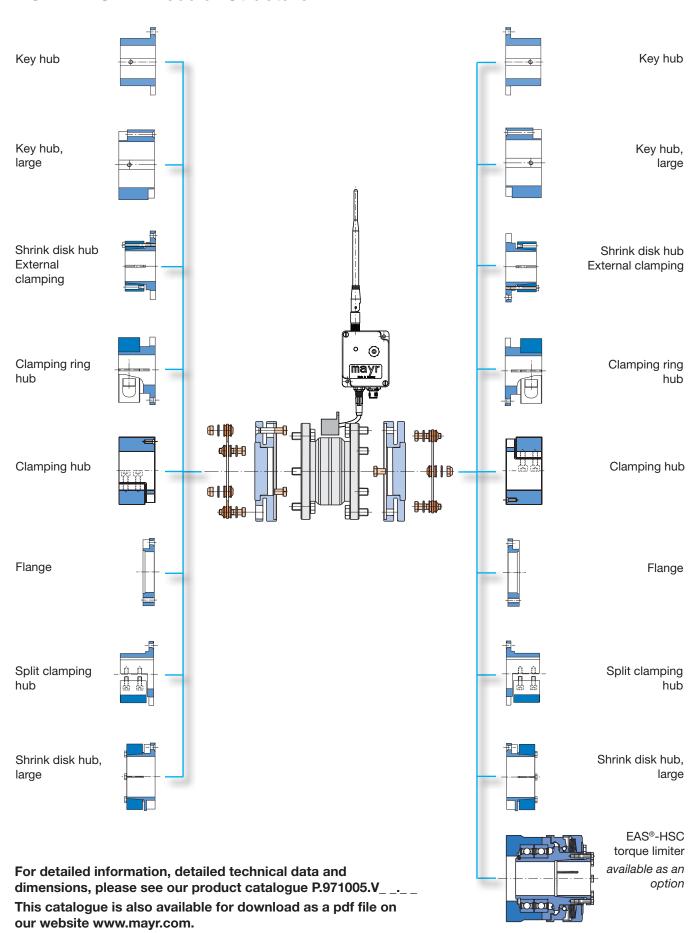
<sup>3)</sup> Valid for unchanging load direction, max. load cycles  $\leq 10^5$ .

<sup>4)</sup> The permitted misalignments may not simultaneously reach their maximum values.

<sup>5)</sup> The values refer to couplings with 2 disk packs.



## **ROBA®-DSM - Modular Structure**





## ROBA®-DSM - the measuring machine element

The areas of application for this torque measurement coupling range from test stand construction through use in serial production machines right up to condition monitoring. The system permits uncomplicated condition monitoring of machines and systems.

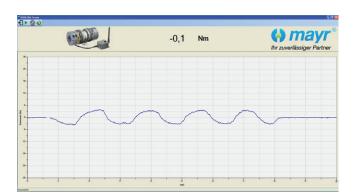
### Valuable data for maximum productivity

- Machine performance data
- Unpermitted operating conditions lying outside the specifications (in case of a defect or reclaim)
- Utilisation or runtime of the machine
- Current operating conditions and condition changes to the machine for preventative maintenance purposes
- Dynamic maintenance intervals dependent on the utilisation

### Highlights and system advantages

- Direct PC connection possible (USB connection)
- Software for visualisation of the measurement values available as an option
- Use without bearings
- Simple installation and set-up
- Low space requirements on the drive line, no torque support required
- Resistant to vibrations and distance changes on the energy transmitter
- Housing and plug-in connector suitable for industrial purposes (protected against water spray)
- High measuring rate of 7000 measurements per second permits the recording of highly-dynamic loads
- Operation of strain sensor without battery via contactless power supply





| Technical Data             | Dimensions                         |                    |                          |       | Si    | ze   |       |
|----------------------------|------------------------------------|--------------------|--------------------------|-------|-------|------|-------|
| Technical Data,            | Dimensions                         |                    |                          | 16    | 40    | 100  | 160   |
| Nominal torque 1) 2)       |                                    | T <sub>KN</sub>    | [Nm]                     | 190   | 450   | 800  | 1600  |
| Peak torque 3)             |                                    | T <sub>KS</sub>    | [Nm]                     | 285   | 675   | 1200 | 2400  |
| Ultimate torque            |                                    | T <sub>KB</sub>    | [Nm]                     | 570   | 1350  | 2400 | 4800  |
|                            | Minimum bore                       | d <sub>K min</sub> | [mm]                     | 20    | 25    | 32   | 40    |
| Clamping hub               | Maximum bore                       | d <sub>K max</sub> | [mm]                     | 45    | 60    | 90   | 100   |
| Clamping nub               | Maximum speed                      | n <sub>max</sub>   | [rpm]                    | 9500  | 7000  | 5100 | 4300  |
|                            | Length torque measurement coupling |                    | [mm]                     | 178.2 | 230.8 | 292  | 329.2 |
| Barrelli and               | Perm. axial displacement 5)6)      | $\Delta K_{a}$     | [mm]                     | 0.8   | 1.1   | 1.5  | 1.7   |
| Permitted misalignments 4) | Perm. angular misalignment 7)      | $\Delta K_{w}$     | [mm]                     | 0.7   | 0.7   | 0.7  | 0.7   |
| illisaligilillellis /      | Perm. radial misalignment 5)       | $\Delta K_r$       | [mm]                     | 1.1   | 1.3   | 1.6  | 1.8   |
| Carina Digidition          | Total torsional rigidity           |                    | [10 <sup>3</sup> Nm/rad] | 36.2  | 114.3 | 320  | 585   |
| Spring Rigidities          | Angular spring rigidity 7)         |                    | [Nm/rad]                 | 229   | 298   | 1089 | 1990  |

| Technical Data for Measuring System                                                                 |                           |  |  |  |  |  |  |
|-----------------------------------------------------------------------------------------------------|---------------------------|--|--|--|--|--|--|
| Supply voltage                                                                                      | 24 VDC (±10 %)            |  |  |  |  |  |  |
| Max. current consumption                                                                            | 1 A                       |  |  |  |  |  |  |
| Measuring signal output (rotational direction right positive, 10V refers to $T_{\mbox{\tiny KN}}$ ) | 0 ±10 V                   |  |  |  |  |  |  |
| Nominal temperature range                                                                           | -20 °C to +70 °C          |  |  |  |  |  |  |
| Temperature drift, zero point                                                                       | 0,04 % of final value / K |  |  |  |  |  |  |
| Temperature drift, measured value                                                                   | 0.03 % of final value / K |  |  |  |  |  |  |

- 1) Other torques and construction sizes available on request.
- 2) Valid for changing load direction as well as for max. permitted shaft misalignment. The following applies for split clamping hubs: Valid for unchanging load direction as well as for max. permitted shaft misalignment. When the load direction changes, max. 60% of the stated nominal torque is permitted.

| Technical Data for Measuring System |                                            |  |  |  |  |  |  |
|-------------------------------------|--------------------------------------------|--|--|--|--|--|--|
| Max. total error                    | < 1 % of final value (< 0.5 % via USB)     |  |  |  |  |  |  |
| Bandwidth                           | 3 kHz (-3 dB)                              |  |  |  |  |  |  |
| Max. dyn. load                      | 100 % of T <sub>KN</sub>                   |  |  |  |  |  |  |
| Protection                          | Receiver/stator IP65<br>Strain sensor IP52 |  |  |  |  |  |  |
| Permitted speed                     | 0 n <sub>max</sub>                         |  |  |  |  |  |  |
| Connection                          | M12 plug, 4-pole                           |  |  |  |  |  |  |

- 3) Valid for unchanging load direction, max. load cycles ≤ 105.
- 4) The permitted misalignments may not simultaneously reach their maximum values.
- 5) The values refer to couplings with 2 disk packs.
- 6) Only permitted as a static or virtually static value.
- 7) The values refer to 1 disk pack.

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