

ACCESSORY BROCHURE

(Without Pricing) Rev: 08/1/23







RS-1
Rolling Robot Stand for OB7 and OB7
Stretch models.



RS-2
Robot Stand (not rolling) for OB7 Max series robot.



PEDESTAL 1Pedestal only for floor mounting OB7 and OB7 Stretch models.



PEDESTAL 2
Pedestal only for floor mounting OB7 Max models.



AT-1
Accessory and assembly table for OB7 and OB7 Stretch models. 28" x 39" Requires RS-1 or pedestal 1for use.



AT-2
Accessory and assembly table for OB7
Max models. 48"x48" Requires RS-2 or
Pedestal 2 for use.





OB VISIONAutomatic Robot Vision for all models of OB7 Robots



DUAL GRIPPER ADAPTER KITFor installing two grippers on OB7.
Compatible with all OB7 models. (Grippers not included.)



PG-2Productive Robotics Parallel Gripper model
2: 90mm opening travel.



IO-2
OB7 interface module: 8 digital or analog inputs (fully isolated), 8 outputs (PNP or NPN isolated): M12 connectors, 2 dry contact SPDT relay outputs (screw termainals).



ROBOT JACKET

Body Cover manufactured from a laminated polyester material. This provides for a water-resistant level of protection. This one piece "sock" design installs oneway by sliding over the robot. Zig-Zag elastic at each end conforms to the robot to hold cover in place.



PG2 FINGER EXTENSIONSExtends PG2 gripper fingers to grip items from 95mm - 180mm.

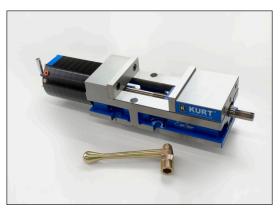




VISE-002
Airvise model pneumatic milling vise 4" jaws. 6" accessory jaws available)



VISE-001
Airvise Model pneumatic milling vise for rotary table use 4" jaws. 6" accessory jaws available)



VISE-006 Kurt Pneumatic milling vise. 6" jaws



PNEU-1
Pneumatic interface module. 0-100PSI,
built in pressure regulator. Requires I/O-2



CHIP FAN-004Chip clearance fan for milling machines.
Requires 3/4" tool holder



AIR BLOW OFF KIT
Air nozzle and adapter for all OB7 model robots. Requires Pneu1 and I/O-2





REMOTE RELAY 1 CHFully isolated remote interface relay.
Requires I/O-2



REMOTE RELAY 2CHFully isolated dual remote interface relay.
Requires I/O-2



LIDAR 1Laser Safety Scanner. For slowing/stopping robot when a person enters the work area. Requires I/O-1 or I/O-2



CABLES-LONG OB7
Long Cable set: 5 meter cable set for locating
OB7 up to 5 meters from robot control
computer. Compatible with all models of OB7





CBL-507: Y CABLE for separating the two inputs or outputs on an M12 connector on I/O-2.



PG2 FINGER SETFor Productive Robotics Parallel Gripper.



PG2 THREE FINGER ADAPTERModifies the PG2 standard gripper to allow centered pickup of round parts.

